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Uses of Methods with Result Verification for Simplified Control-Oriented SOFC Models

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Introduction			

SOFC: Devices converting chemical energy into electricity

An important characteristic: Temperature!

Control-oriented models: ODEs with unknown parameters to be identified from real-life data

 $\begin{array}{ll} \mbox{Identification: Least squares/Global optimization} \\ \Phi(p) = \sum\limits_{k=1}^{T\approx 17500} \sum\limits_{j=1}^{n_m} \Big(\underbrace{y_j(t_k,p)}_{\mbox{solution to ODEs}} & -\underbrace{y_{j,m}(t_k)}_{\mbox{measured data}} \Big)^2 \rightarrow \min \end{array}$

Traditional techniques: y(t, p) reflects only stationary operating states

---- Goal: Models for a range of operating conditions (better control!)

A cooperation with the University of Rostock

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Result Verification for Simplified SOFC Models



SOFC stack: A distributed parameter system naturally described by a non-linear partial differential equation

Control-oriented models: ODEs obtained by spatial semi-discretization Difficulty: The temperature can be measured only at few positions \rightsquigarrow State/disturbance estimators are necessary

Basic control inputs: Gas preheaters (modeled or from measurements) Types of models: Different kinds in dependence on

- the used arithmetics (floating point/interval/other)
- "accuracy" of the solution y(t,p) (analytic/approximated/exact)

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(Still) Modeling Temperature $\theta(t)$ for SOFCs

Important for θ : Heat capacities of gases modeled as $c_{gas}(\theta) = c_{gas,0} + c_{gas,1} \cdot \theta + c_{gas,2} \cdot \theta^2$

Example of a model with (just) one finite volume element:

dtheta(1.1) = T AG inv*(v N2 d-v N2-d N2 sch):dtheta(2.1) = T SL AG inv*(v N2-v N2 in):dtheta(3.1) = 0: $dtheta(4,1) = T_AG_inv*(v_H2_d-v_H2_d_H2_sch); dtheta(5,1) = T_SL_AG_inv*(v_H2-v_H2_in); dtheta(6,1) = 0;$ dtheta(7,1) = T_AG_inv*(v_H20_d-v_H20_d_H20_sch);dtheta(8,1) = T_SL_AG_inv*(v_H20-v_H20_in);dtheta(9,1) = 0; dtheta(10.1) = T CG inv*(v CG d-v CG-d CG sch):dtheta(11.1) = T SL CG inv*(v CG-v CG in):dtheta(12.1) = 0: dtheta(13,1)=-c_m_inv*(-234000*alpha_i*z*F*theta_A-448500*alpha_j*z*F*theta_A-I_ges^2*R_el*z*F -z*F*v_CG_in*c_CG_0+234000*alpha_i*z*F*theta_1_1_1-z*F*v_N2_in*c_N2_0-345000*alpha_k*z*F*theta_A +448500*alpha j*z*F*theta 1 1 1+345000*alpha k*z*F*theta 1 1 1-z*F*v H20 in*c H20 1*theta 1 1 1 -z*F*v H20 in*c H20 2*theta 1 1 1^2+z*F*m dot AG H20 in*theta 1 1 1*c H20 0+z*F*m dot AG H20 in* theta_1_1^2*c_H20_1+z*F*m_dot_AG_H20_in*theta_1_1^3*c_H20_2-I_ges*R_delta_H_H2_0-z*F*v_H2_in* c_H2_1*theta_1_1_1-z*F*v_H2_in*c_H2_2*theta_1_1_1^2+z*F*m_dot_AG_H2_in*theta_1_1_1*c_H2_0+ z*F*m dot AG H2 in*theta 1 1 1^2*c H2 1+z*F*m dot AG H2 in*theta 1 1 1^3*c H2 2+z*F*m dot CG in* theta_1_1_1*c_CG_0-z*F*v_CG_in*c_CG_2*theta_1_1_1^2-z*F*v_CG_in*c_CG_1*theta_1_1_1+z*F*m_dot_CG_in* theta_1_1_1^3*c_CG_2-I_ges*R_delta_H_H2_1*theta_1_1_I-I_ges*R_delta_H_H2_2*theta_1_1_1^2 +z*F*m dot CG in*theta 1 1 1^2*c CG 1-z*F*v N2 in*c N2 1*theta 1 1 1+z*F*m dot AG N2 in *theta_1_1_1^3*c_N2_2-z*F*v_N2_in*c_N2_2*theta_1_1_1^2+z*F*m_dot_AG_N2_in*theta_1_1_1*c_N2_0+ z*F*m dot AG N2 in*theta 1 1 1^2*c N2 1-z*F*v H2 in*c H2 0-z*F*v H20 in*c H20 0)/z/F:

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Idea: Simplify the models, but not too much (wide range!)

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Idea: Simplify the models, but not too much (wide range!)

Approach: $c_{gas}(\theta) = c_{gas,0}$ or $c_{gas}(\theta) = c_{gas,0} + c_{gas,1} \cdot \theta \leftarrow \text{Topic 1}$

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How Good are the Simplified Models?

Question 0: How good is the correspondence to reality? What about the validity range?

Question 1: Can we take uncertainty in parameters into account?

Question 2: Can we find out which parameters these models are most sensitive to?

Question 3: Is it possible/useful to solve the equations analytically?

Approaches to answers \leftarrow Topic 2:

- $1 \rightarrow$ Result verification (intervals, affine forms, Taylor models)
- $2 \rightarrow$ Sensitivity analysis (compute $\frac{\partial \theta}{\partial p_i}$)
- $3 \rightarrow \mbox{ Yes}$ in some cases

Tool: $\operatorname{UNIVERMEC}$ allowing for an easy reuse and flexibility

Introduction	
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Characteristics of SOFC Temperature Models

$$\Phi(p) = \sum_{k=1}^{T} \sum_{j=1}^{n_m} \left(\underbrace{\theta_j(t_k, p)}_{\text{orbiting to ODE}} - \underbrace{\theta_{j,m}(t_k)}_{\text{orbiting to ODE}} \right)^2 \to \min$$

solution to ODEs

measured data

F1 How exactly is $\theta(t_k, p)$ obtained?

- F1.a A closed-form solution
- F1.b Approximation by an expression (e.g., with the Euler method)
- F1.c Numerical solution from a "black-box" solver
- F2 What is the underlying technique for the implementation?
- F2.a Floating point F2.b Interval F2.c Other verified Examples: High verification degrees F1.b& F2.b-c "Verified approximation" F1.c&F2.b Verified IVP solvers
 - [+] Rounding cared for
 - [-] Overestimation
 - [+] Easy derivatives (AD)
 - $\left[+\right]$ Easily portable to the GPU

- [+] Verifies the whole model
 - [+] Verifies the whole model
 - [-] Derivatives require solving
 - an additional ODE
 - [-] High computational effort

Good: UNIVERMEC allows us to implement all combinations

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Result Verification for Simplified SOFC Models

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Simplified Models			

Trade-off between verification degree and computing time necessary $\downarrow\downarrow$

Higher verification degrees in real-time \rightsquigarrow Model simplification

Simplifying assumptions

- $\rightarrow\,$ The nitrogen is the only anode gas for the heating phase
- $\rightarrow~$ One volume element for the whole stack
- → Heat capacities of all gases are constant $(c_{gas}(\theta) = c_{0,gas})$ or linear $(c_{gas}(\theta) = c_{0,gas} + c_{1,gas} \cdot \theta)$

Generally, we are interested in all combinations of F1& F2 Actually, we consider F1.a-b with

F2.a for parameter identification F2.a-c for simulation

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Parameters to Be	Identified		

$lpha_i$, $lpha_j$, $lpha_k$	coefficients of heat convection
$c_{N_2,0}$, $c_{N_2,1}$	heat capacity of N_2 as $c_{N_2}(heta)=c_{N_2,0}(+c_{N_2,1}\cdot heta)$
с _{СС,0} , с _{СС,1}	heat capacity of the cathode gas
T_{AG}^{inv}	inverse time constant of the anode gas preheater
T_{CG}^{inv}	inverse time constant of the cathode gas preheater
$T^{inv}_{SL,AG}$	inverse time constant of the anode gas supply line
$T^{inv}_{SL,CG}$	inverse time constant of the cathode gas supply line
С	specific heat capacity of the stack module
m	mass of the stack module
c_m^{inv}	$=rac{1}{c\cdot m}$ with the mass m and heat capacity c of the stack

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Control Variables			

- $\dot{m}_{N_2}^{in}$ mass flow of anode gas (recorded data)
- \dot{m}_{CG}^{in} mass flow of cathode gas (recorded data)
- $heta_A$ ambient temperature
- $\begin{array}{ll} \theta^d_{AG} & \mbox{desired temperature of the anode gas (recorded data)} \\ \theta^d_{CG} & \mbox{desired temperature of the cathode gas (recorded data)} \\ u_1 = v^d_{N_2} & \mbox{desired } v_{N_2} = \theta^d_{AG} \cdot \dot{m}^{in}_{N_2} \\ u_2 = v^d_{CG} & \mbox{desired } v_{CG} = \theta^d_{CG} \cdot \dot{m}^{in}_{CG} \end{array}$

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The Simplified Model with $c_{gas}(\theta) = c_{0,gas}$

Solution:
$$y_0(t) = u_1 - (u_1 - y_0^{\text{ic}})e^{-T_{\text{NG}}^{\text{inv}}(t-t_0)}$$

 $y_1(t) = u_1 - \frac{T_{\text{SL,AG}}^{\text{inv}}}{T_{\text{SL,AG}}^{\text{inv}} - T_{\text{AG}}^{\text{inv}}} (u_1 - y_0^{\text{ic}})e^{-T_{\text{AG}}^{\text{inv}}(t-t_0)} + k_{\text{N2}}e^{-T_{\text{SL,AG}}^{\text{inv}}(t-t_0)},$
 $\theta(t) = \mathcal{I}_{\text{N2}}(t) + \mathcal{I}_{\text{CG}}(t) + k_{\theta}e^{-c_m^{\text{inv}} \cdot k_{\text{lin}}(t-t_0)} - \frac{k_{\text{const}}}{k_{\text{lin}}},$

with defined expressions for $k_{\rm N2},\, \mathcal{I}_{\rm N2/CG}(t),\, k_{\theta}$

The MATLAB-generated solution is too unstable!

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Result Verification for Simplified SOFC Models

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Simplification 00000 The Simplified Model with $c_{aas}(\theta) = c_{0,aas} + c_{1,aas} \cdot \theta$ ODEs for preheaters \rightsquigarrow a Riccati equation for θ Measured values for preheaters \rightsquigarrow an expression for θ Model: $\dot{\theta} = -c_m^{inv} \cdot (k_{co} + k_{lin}\theta + k_{sa}\theta^2)$ with $k_a = (234\alpha_i + 448.5\alpha_i + 345\alpha_k) \cdot 10^3, \ k_{co} = -\theta_A k_a - (y_{3,m} c_{CG,0} + y_{1,m} c_{N_2,0})$ $k_{lin} = k_a + \dot{m}_{CG}^{in} \cdot c_{CG,0} + \dot{m}_{N_2}^{in} \cdot c_{N_2,0} - (y_{3,m}c_{CG,1} + y_{1,m}c_{N_2,1})$ $k_{sq} = \dot{m}_{CG}^{in} \cdot c_{CG,1} + \dot{m}_{N_2}^{in} \cdot c_{N_2,1}$ Solution in dependence on $D = k_{lin}^2 - 4 \cdot k_{co} \cdot k_{sa}$

$$\begin{split} D > 0: \theta(t) = & \frac{\sqrt{D}/k_{sq}}{1 - e^{-c_m^{inv}(t-t_0)\sqrt{D}} \cdot \left(1 - \frac{2\sqrt{D}}{2k_{sq}\theta^{ic} + k_{lin} + \sqrt{D}}\right)} - \frac{k_{lin} + \sqrt{D}}{2k_{sq}} \\ D < 0: \theta(t) = & \frac{\sqrt{-D}\tan\left(-\frac{\sqrt{-D}}{2}c_m^{inv}(t-t_0) + \theta^c\right) - k_{lin}}{2k_{sq}} , \ \theta^c = \operatorname{atan}\left(\frac{2k_{sq}\theta^{ic} + k_{lin}}{\sqrt{-D}}\right) \end{split}$$

$$D = 0: \theta(t) = \frac{2\theta^{ic} + k_{lin}/k_{sq}}{2 + c_m^{inv}(t - t_0)(2k_{sq}\theta^{ic} + k_{lin})} - \frac{k_{lin}}{2k_{sq}}$$

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Overview			

Two stages: Parameter identification and simulation Two models: M1 ($c_{aas}(\theta) = c_{0,aas}$) and M2 ($c_{aas}(\theta) = c_{0,aas} + c_{1,aas} \cdot \theta$) Identification: Goal A parameter set p with the smallest $\Phi(p)$ Possibilities: Analytical solution (F1.a) or approximation (F1.b) with doubles/intervals (F2.a-b) Note: F1.c is still too expensive computationally (\rightarrow parallelization) Means: MATLAB; IPOPT and GlobOpt in UNIVERMEC Simulation: Goals Identify p_{s} the models are most sensitive to; take into account uncertainty

Possibilities: Analytical (F1.a) or numerical (F1.c) solution with doubles/intervals/AA/TM (F2.a-c)

Note: F1.b is not interesting here!

This helps to identify the overall usage areas for M1 and M2!

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UNIVERMEC: Function Specification

Important: Interoperability

The capability to communicate, execute programs, or transfer data among various functional units in a manner that requires the user to have little or no knowledge of the unique characteristics of those units

Necessary: Formalizations for arithmetics, types of enclosures, etc.



 $f : \mathbb{R}^n \mapsto \mathbb{R}^m, \text{ tools for user-defined}$ functions (inductive), analytical expressions or C++ code blocks

Function extensions: Evaluated with all arithmetics supported by core Features: set of functionalities associated with f (e.g., differentiability) FR object: Tuple $F_{f,n,m} = (\mathcal{I}, \mathcal{F})$ where \mathcal{I} is the set of inclusion functions, \mathcal{F} is a choice out of r supported features

If ${\mathcal I}$ and ${\mathcal F}$ are defined appropriately, e.g., probabilistic arithmetics can be used!

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Parameter Identification

The best obtained parameter sets for M1 and M2 $\,$

Model	M1 (F1.a&F2.a)	M2 (F1.b&F2.a)
с	$4.53503 \cdot 10^{6}$	$3.38579 \cdot 10^4$
$\alpha_i = \alpha_j = \alpha_k$	$1.49548 \cdot 10^{-3}$	$3.60235 \cdot 10^{-5}$
$c_{N_{2},0}$	$1.96452 \cdot 10^{6}$	$5.52725 \cdot 10^{6}$
$c_{N_2,1}$	-	-11221.8
$c_{CG,0}$	$1.52826 \cdot 10^{7}$	$-8.88817 \cdot 10^4$
$c_{CG,1}$	-	483.868
e	3.5K	0.5K





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Comparison			

Difference btw. measured and simulated temperatures in K

Temperature modeled by M1 and M2 (F2.a)



M2 seems to be even better than the normal model!

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Sensitivity			

Sensitivities are obtained easily in UNIVERMEC by algorithmic differentiation

 $\left|\frac{\partial\Phi}{\partial c}\right|$ $\left|\frac{\partial\Phi}{\partial\alpha_{i}}\right|$ $\left|\frac{\partial\Phi}{\partial c_{N_{2},0}}\right|$ $\left|\frac{\partial\Phi}{\partial c_{N_{2},0}}\right|$ Φ $\partial c_{CG,1}$ $3.81 \cdot 10^{10}$ $2.94 \cdot 10^{1}$ $4.96 \cdot 10^{-2}$ $2.64 \cdot 10^{1}$ 1.47 $1.26 \cdot 10^{2}$ F1.a, M2 F1.b, M2 $4.77 \cdot 10^{-3}$ $6.88 \cdot 10^5$ $5.36 \cdot 10^{-5}$ $2.21 \cdot 10^{-2}$ $1.30 \cdot 10^{-3}$ $5.25 \cdot 10^{-1}$ F1.a, M1 $3.09 \cdot 10^{-1}$ $2.45 \cdot 10^8$ $8.49 \cdot 10^{-2}$ - $1.36 \cdot 10^{-1}$ F1.b, M1 $3.09 \cdot 10^{-1}$ $2.45 \cdot 10^{8}$ $8.49 \cdot 10^{-2}$ $1.36 \cdot 10^{-1}$

 \rightarrow Both models are most sensitive to α_i , α_j , α_k

ightarrow For M1, almost no difference in sensitivity between F1.a and F1.b

ightarrow For M2, F1.b is up to 10^5 less sensitive

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Uncertainty

Fact: We were intereseted in $c_{gas}(\theta) = c_{0,gas}(+c_{1,gas} \cdot \theta)$ Consider uncertainty in $c_{N_2,0}$ and $c_{CG,0}$



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Conclusion			

What did we do?

- \rightarrow Simplified models for SOFC temperature wrt. heat capacity of gases with analytical solutions considered
- ightarrow Parameter sets with $e_{M1}=3.5$ K and $e_{M2}=0.5$ K identified

 \rightarrow Models analysed wrt. to their areas of validity (F1.ab / F2.abc) What did we gain?

- M1: F1.a-b are equivalent; good for short time intervals; fast
- M2: Very good correspondence with measured data; F1.a structurally complex (but fast)
- \rightarrow $\,$ M1,M2 are very sensitive to coefficients of heat convection
- ightarrow M1,M2 handle different magnitudes of uncertainty in $c_{gas,0}$
- ightarrow M2 with F1.a more prone to overestimation than M1

What now?

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Outlook			

Goal 1: More verification (\rightsquigarrow consider F1.c)

Goal 2: Less overestimation (→ subdivide uncertainty regions) Possible solution: Use the GPU to speed up computations!



Reference system:

Xeon E5-2680, 8 cores, gcc 4.7 on Linux, GeForce GTX 580, 512 cores, CUDA 4.2

Results (evaluation of $\Phi([p])$):

 $1 \times 1 \times 1$: speedup of 19

 $1\times 3\times 1:$ speedup of 30

 $3\times3\times1:$ speedup of 33

Problem: Software! Besides: Models for degradation of SOFC stacks?