



BAYESIAN CALIBRATION OF LATTICE DISCRETE PARTICLE MODEL FOR CONCRETE

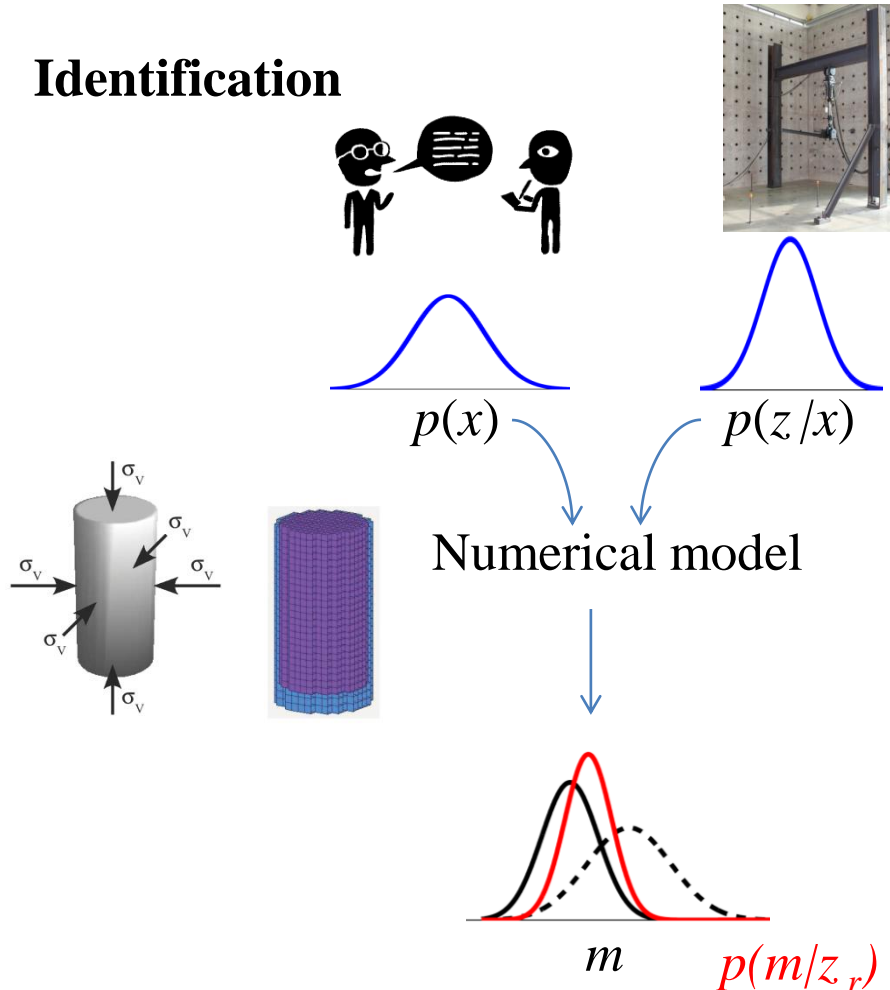
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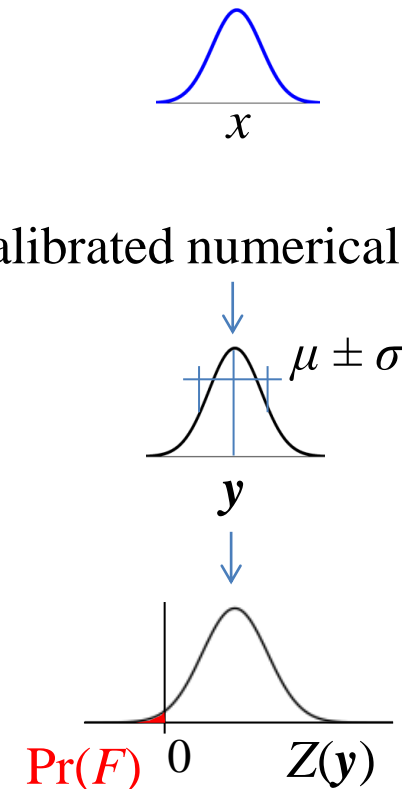


- Reducing uncertainties in input parameters
- Investigation of uncertainties in structural reliability analysis

Identification



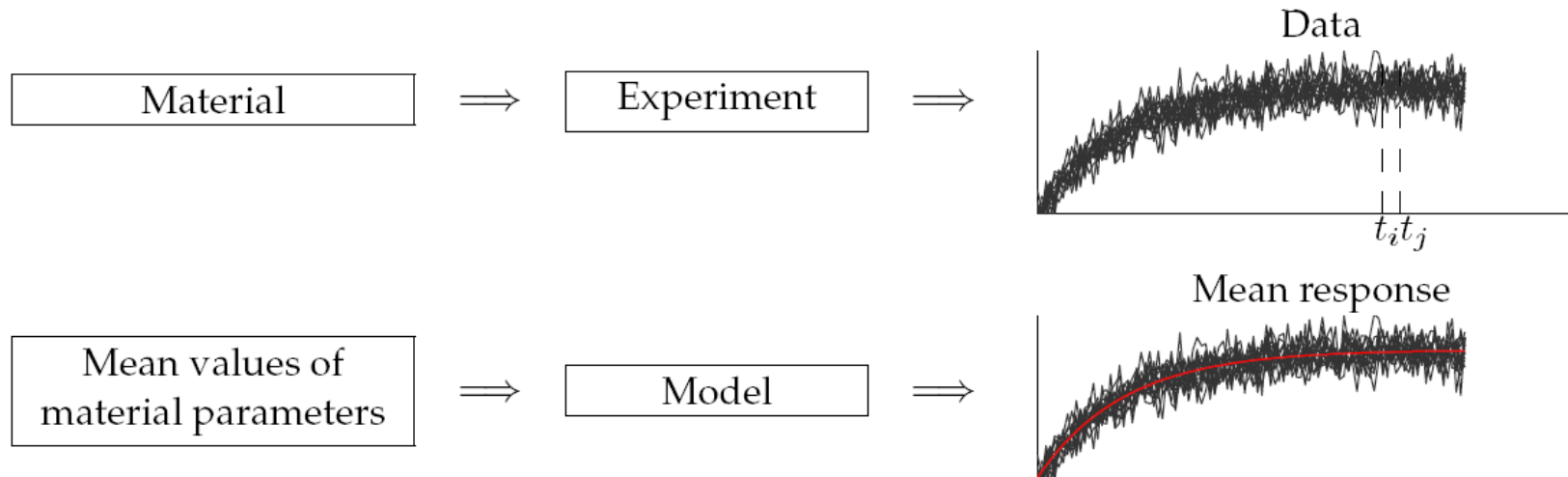
Reliability analysis





Fitting the model response to experimental data

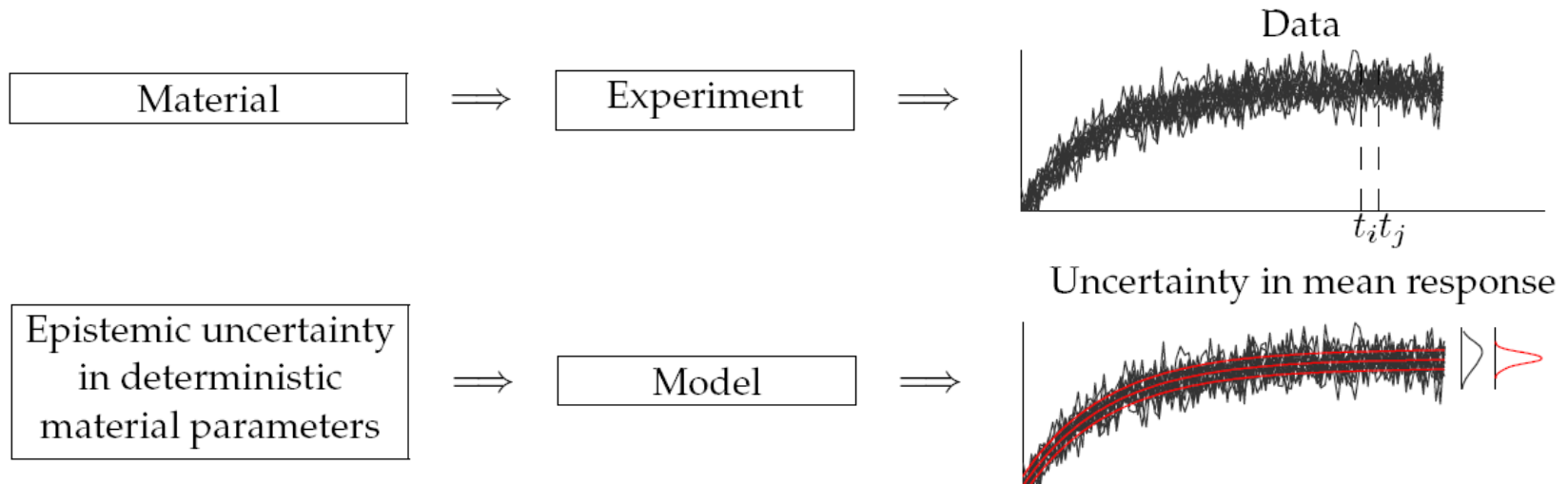
- The most common approach of parameter estimation
- Parameter optimisation (ill-posed problem) – robust optimisation algorithms





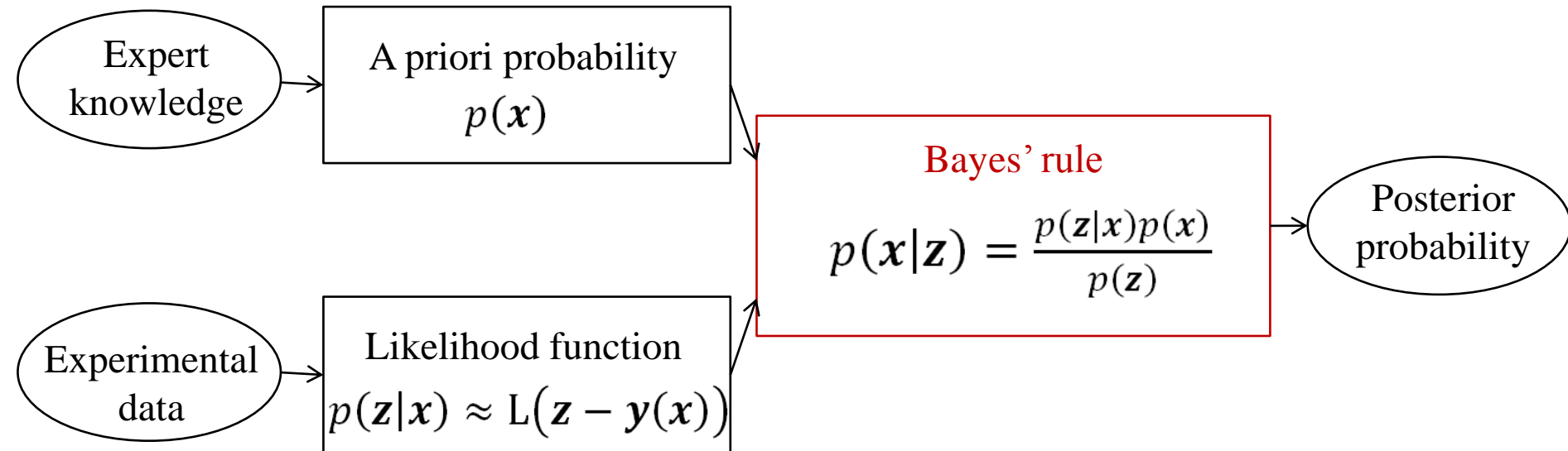
Quantification of epistemic uncertainties

- Epistemic (reducible, subjective) uncertainty about deterministic values
- Bayesian approach combining all available information
- Well-posed identification problem





Setting of Bayesian approach



$$z(x, \omega) = y(x) + \varepsilon(\omega)$$

Data

Random
observations

Model response

Often a black-box function
Expensive to evaluate

Measurement error

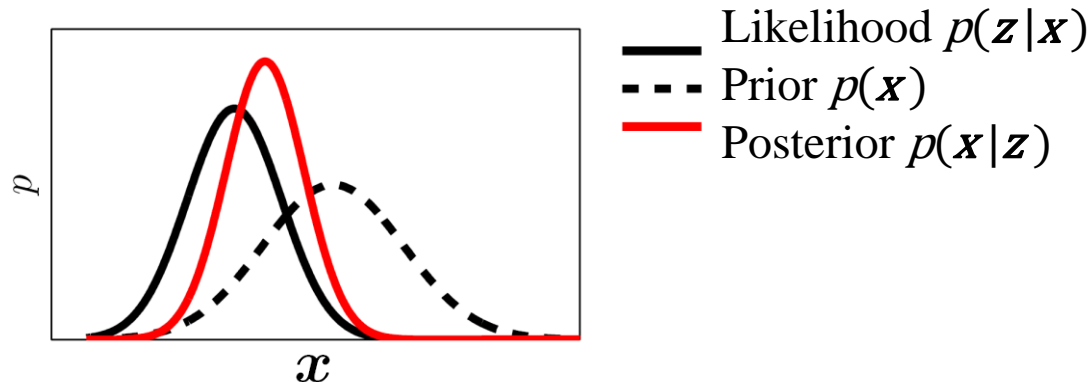
Usually $\varepsilon \sim N(0, \Sigma)$

x – model parameters to be identified



Methods of computing Bayesian posterior

$$p(\mathbf{x}|\mathbf{z}) = \frac{p(\mathbf{z}|\mathbf{x})p(\mathbf{x})}{p(\mathbf{z})} = \frac{p(\mathbf{z}|\mathbf{x})p(\mathbf{x})}{\int p(\mathbf{z}|\mathbf{x})p(\mathbf{x})d\mathbf{x}} \approx L(\mathbf{z} - \mathbf{y}(\mathbf{x})) p(\mathbf{x})$$

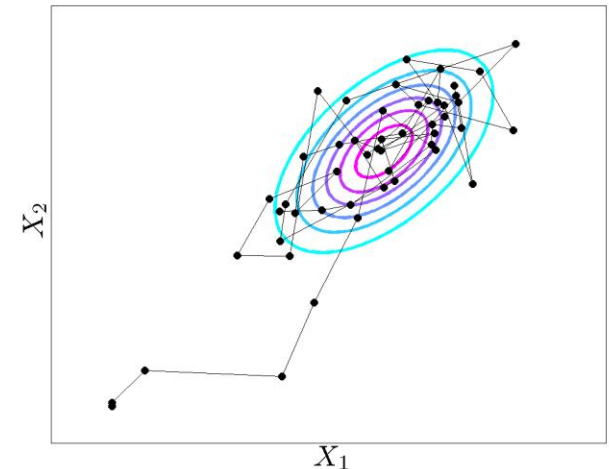


- Markov chain Monte Carlo
- Kalman filter
- Optimal maps



Features of the method

- Sampling procedure based on model simulations, suitable for nonlinear models
- Markov chain of required stationary distribution equal to the posterior
- Different algorithms:
 - Gibbs sampler
 - Metropolis-Hasting algorithm
 - Metropolis algorithm



Disadvantages

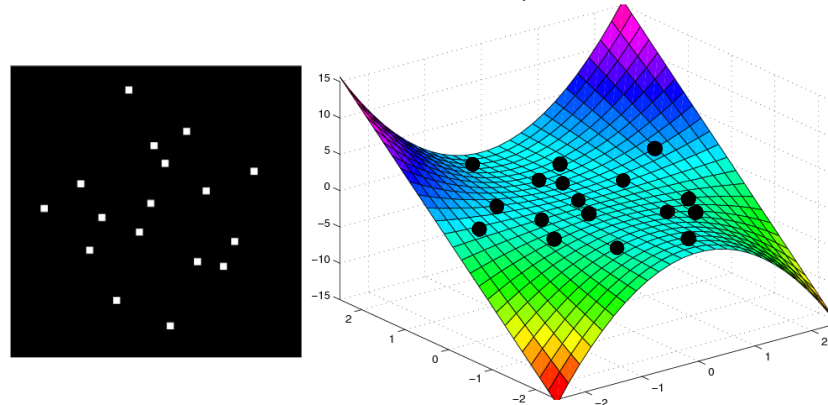
- Low convergence of the method → appropriate setting of the algorithm:
 - Proposal distribution
 - Starting point / burn-in period
- High computational effort → Model approximation:
 - Neural network, radial basis function, kriging, polynomial chaos expansion



Approximation of a model response

$$\widetilde{PC}(x(\xi)) = \sum_{\alpha} \beta_{\alpha} \psi_{\alpha}(\xi)$$

- Respect to probability distribution of random variables
 - Hermite polynomials – Gaussian, Legendre polynomials – Uniform
- Methods for construction of PCE-based approximation
 - Linear regression, stochastic Galerkin method, stochastic collocation method
- Efficient evaluation of statistical moments, Jacobian and Sobol' sensitivity indices





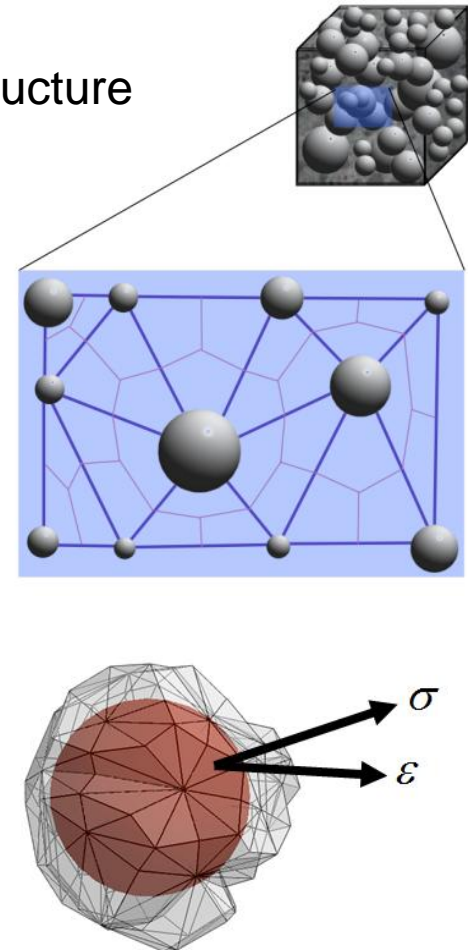
[Cusatis, 2011]

Lattice discrete particle model for concrete

- A priori volume discretization is performed taking into account material heterogeneity (coarse aggregate pieces)
- Parameters governing the generation of concrete meso-structure

material property		unit	value
minimum particle size	d_0	mm	4
maximum particle size	d_a	mm	16
cement content	c	kg/m ³	240
water to cement ratio	w/c	-	0.83
aggregate to cement	a/c	-	8.83
Fuller coefficient	n_F	-	0.5
concrete density	ρ	kg/m ³	2400

- Randomly generated concrete granulometric distribution acts as a noise in the model response





Parameters to be identified and their prior distribution

material property		unit	value (range)
normal modulus	E_0	MPa	20000 – 70000
shear-normal coupling	α	-	0.2 – 0.3
tensile strength	σ_t	MPa	1.5 – 5
tensile characteristic length	l_t	mm	50 – 300
softening exponent	n_t	-	0.1 – 1
shear/strength ratio	σ_s/σ_t	-	1.5 – 8
initial friction	μ_0	-	0.001 – 0.5
compressive strength	σ_{c0}	MPa	$\sigma_{c0} = 40\sigma_t$
transitional stress	σ_{N0}	MPa	$\sigma_{N0} = 240\sigma_t$

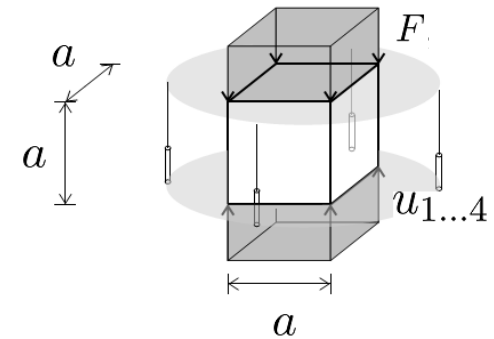


Experimental data

– Uniaxial compression test

- 3 repetitions
- Nominal stress discretised into 250 strain steps

$$\sigma_N = \frac{F}{a^2} \quad \text{and} \quad \varepsilon_N = \frac{u}{a}$$



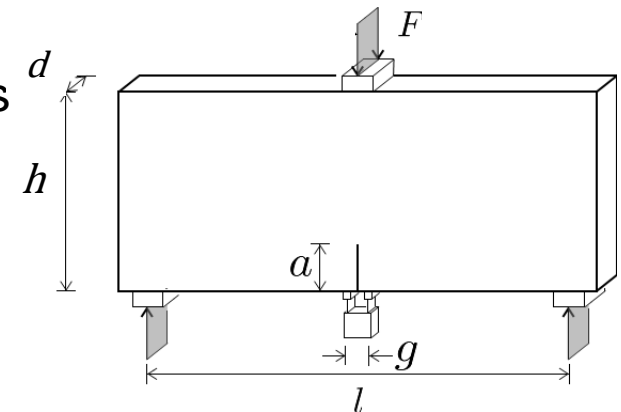
– Notched three-point-bending test

- 4 repetitions
- Nominal stress discretised into 250 strain steps

$$\sigma_N = \frac{3Fl}{dh^2} \quad \text{and} \quad \varepsilon_N = \frac{CMOD}{h}$$

- Elastic stiffness K

$$\varepsilon_N^{\text{inel}} = \varepsilon_N - \sigma_N (1/K)$$





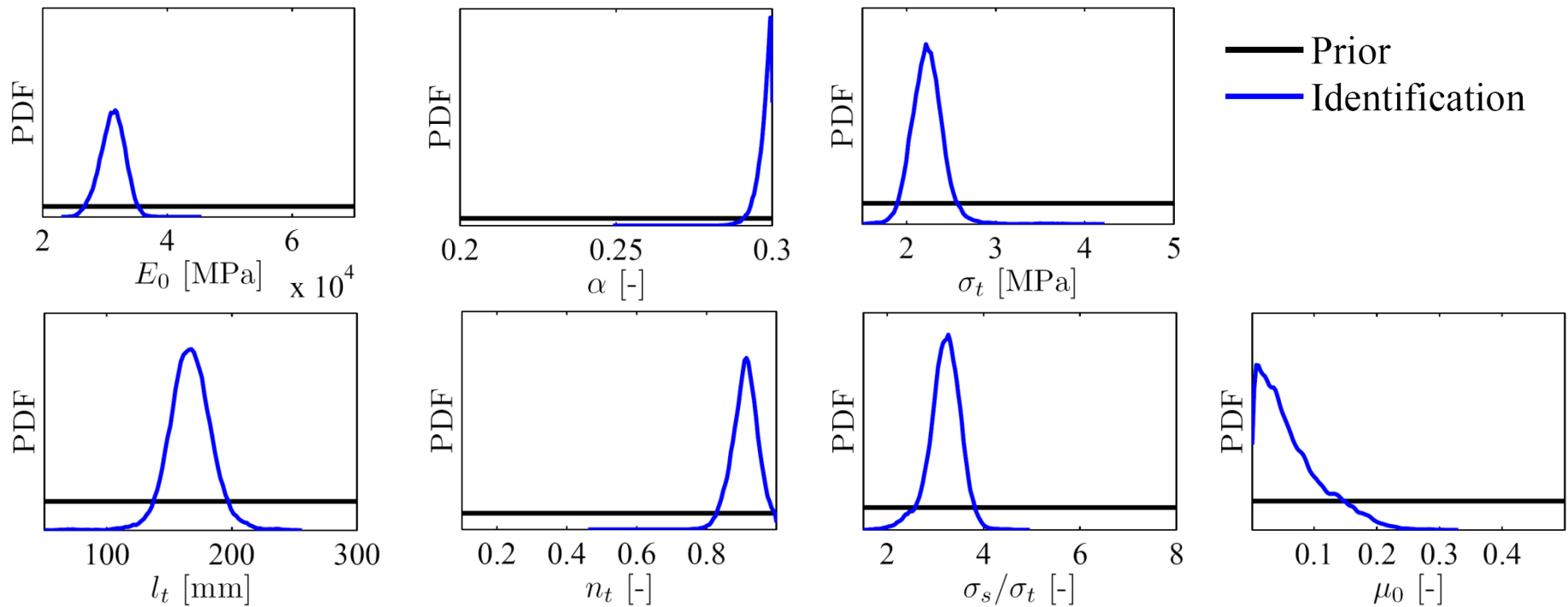
Bayesian posterior estimate

- Uniform prior distribution
- Normal distribution of experimental errors
 - Compression test: $\varepsilon_{\sigma_N} \sim N(0, 8^2)$
 - Three-point bending test: $\varepsilon_{\sigma_N} \sim N(0, 2^2)$, $\varepsilon_K \sim N(0, 2880^2)$
- MCMC sampling
 - Metropolis algorithm, 500,000 samples
- PCE-based model approximation
 - Legendre polynomials of third degree
 - Linear regression based on 200 full model simulations
 - Elimination of the noise caused by random distribution of particles



Identified parameters' PDF

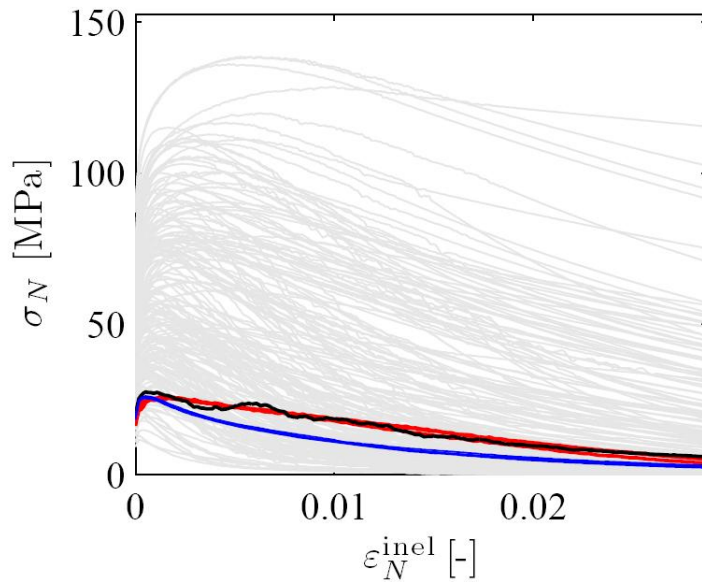
	E_0 [MPa]	α [-]	σ_t [MPa]	l_t [mm]	n_t [-]	σ_s/σ_t [-]	μ_0 [-]
MEAN	31183	0.297	2.236	166.6	0.910	3.192	0.063
STD	1998	0.003	0.193	17.8	0.037	0.338	0.051



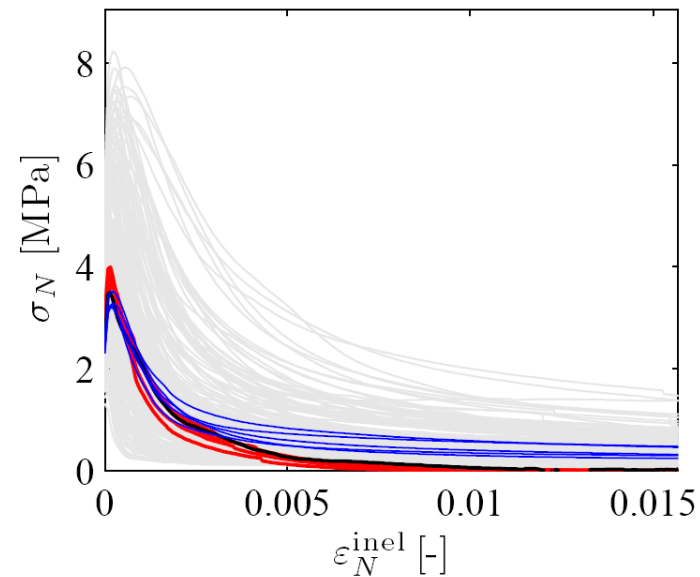


Comparison of model response and experimental data

- Training simulations
- Experiments
- Identified PCE response
- Identified response



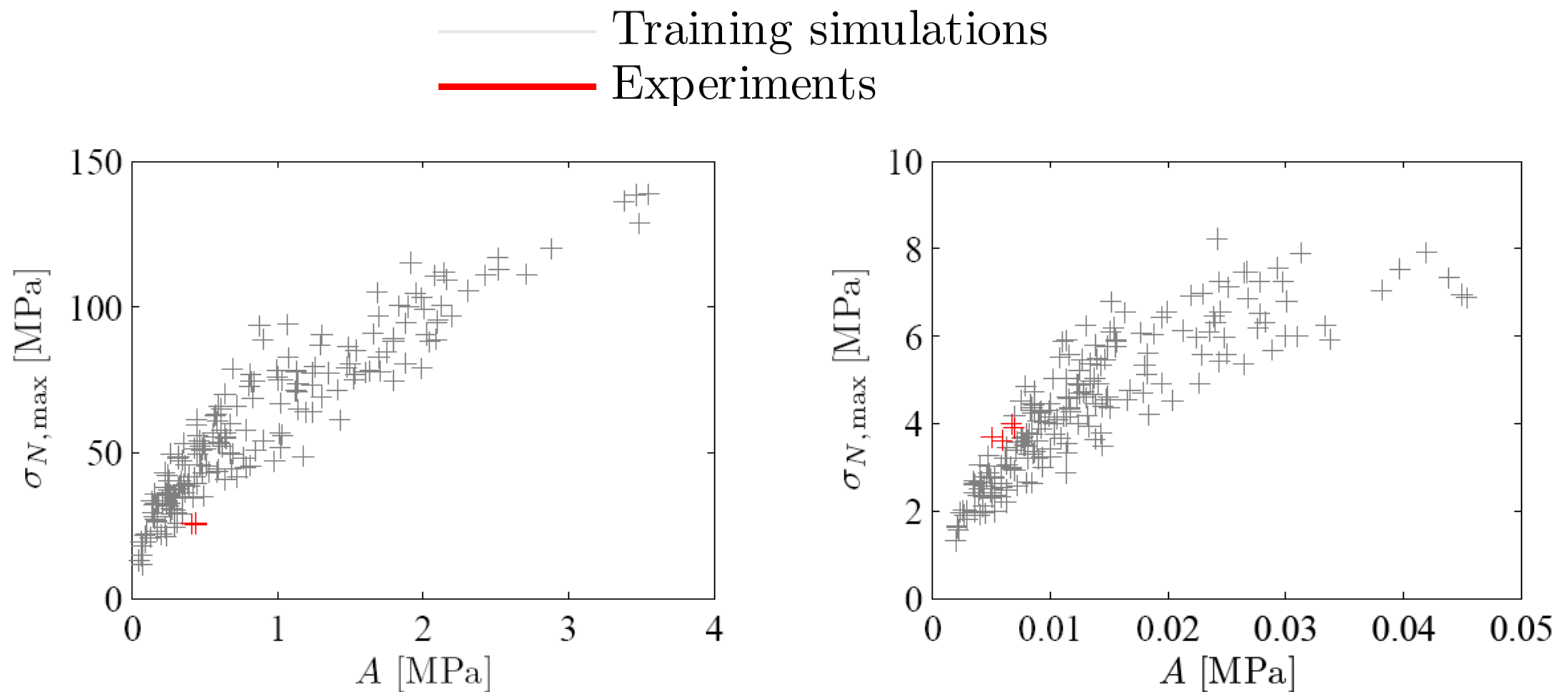
Uniaxial compression test



Three-point-bending test



Inappropriate choice of prior bounds



Uniaxial compression test

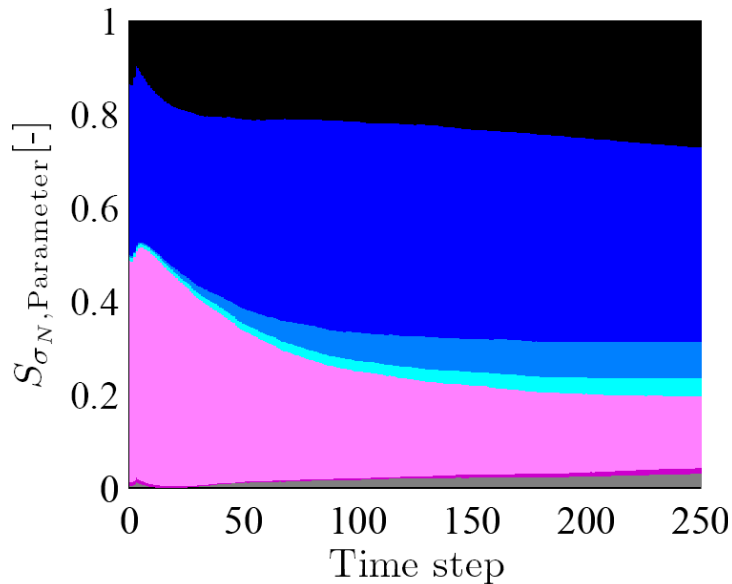
Three-point-bending test

$$A = \int \sigma_N d\varepsilon_N$$

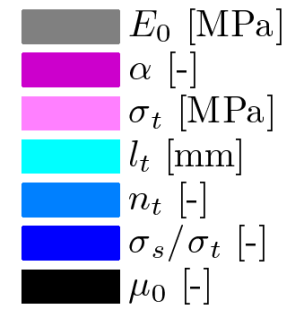
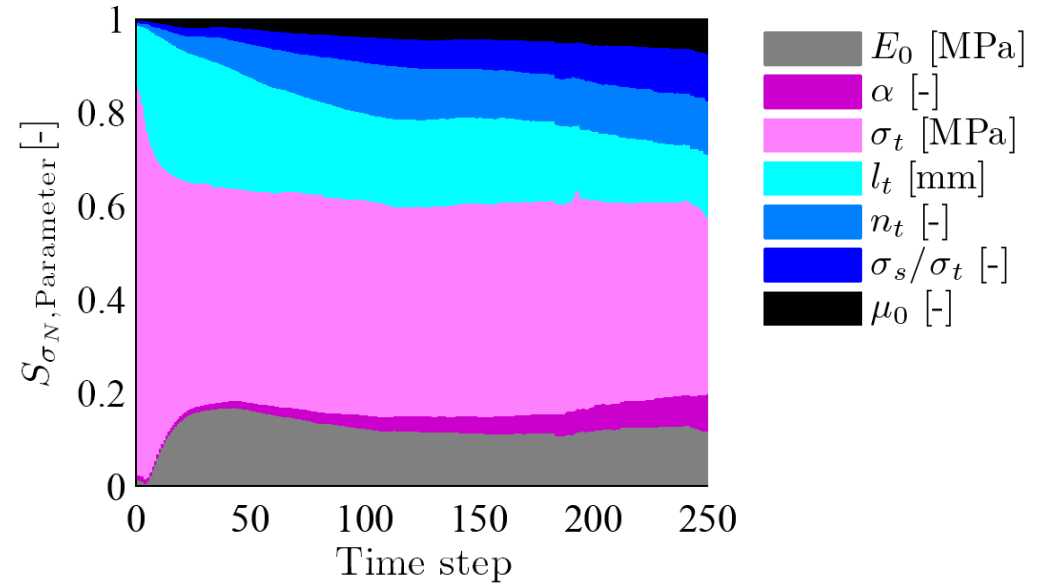


Sensitivity analysis

Uniaxial compression test



Three-point-bending test





Bayesian model calibration

- **Combination of prior knowledge and noisy experimental observations**
 - Estimation of unknown model parameters
 - Probabilistic description of epistemic uncertainty in deterministic values
- **MCMC – Sampling procedure**
 - Versatile, model-independent, computationally exhaustive method
- **Polynomial chaos-based approximation**
 - Acceleration of identification procedure, sensitivity analysis
- **Calibration of lattice discrete particle model**
 - Inaccurate approximation in the region of experimental data caused by inappropriate choice of prior distribution
 - Prescription of a new prior ranges to obtain the necessary information for constructing the accurate model approximation



THANK YOU FOR YOUR ATTENTION.

Aknowledgements

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